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NOTES ON THE  $n$ -PERSON GAME, IV:  
A THEOREM ON C-STABLE SETS

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Summary: Solutions are obtained to the following set-equation, relevant to n-person game theory:

$$X = C - (X+R),$$

where  $C$  and  $R$  are respectively a convex set and a cone in an  $n$ -dimensional vector space, satisfying certain conditions.

#### NOTES ON THE $n$ -PERSON GAME, IV:

##### A THEOREM ON $C$ -STABLE SETS

L. S. Shapley

The theory of stable-set solutions to  $n$ -person games<sup>\*</sup> focuses attention on the somewhat more general question of determining conditions on  $C$  and  $R$  to ensure the existence of solutions to the equation

$$(1) \quad X = C - (X+R)$$

where  $X$ ,  $C$ , and  $R$  are point sets in an  $n$ -dimensional vector space  $E^n$ ;  $0 \notin R$ ; and  $(X+R)$  is the set of points  $x + r$ ,  $x \in X$ ,  $r \in R$ .

Intuitively,  $C$  may be regarded as a space of alternatives,  $R$  as an intransitive preference rule, whereby  $y$  is preferred to  $x$  if and only if  $x - y$  is in  $R$ , and  $X$  as a

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\* See the third note of this series: "Some variants of the von Neumann-Morgenstern definition of solution", RM-817.

set of conventional choices. When  $X$  satisfies (1) we say that  $X$  is  $C$ -stable with respect to  $R$ . If  $R$  is a convex cone, then we get a partial ordering of the alternatives, and the only  $C$ -stable set is the set of maximal elements in  $C$ .

In this note we obtain solutions for (1) under the conditions that  $C$  be convex (in a strong sense described below), and that  $R$  be a cone, large enough so that every point will be comparable with points near any other point, but still permitting a hyperplane of mutually incomparable points.\*\* The solutions obtained resemble the "discriminatory" solutions of von Neumann and Morgenstern.

If  $H$  is any hyperplane through the origin of  $E^n$ , we arbitrarily label the two associated open half-spaces  $H^+$  and  $H^-$ . The translated hyperplane of points  $h + x$ , where  $x$  is a fixed vector perpendicular to  $H$ , and  $h$  ranges over  $H$ , we denote by  $H_c$ , where  $|c|$  is the length of  $x$  and  $c > 0$  if  $x$  is in  $H^+$ ,  $c < 0$  if  $x$  is in  $H^-$ .  $H_c^+$  and  $H_c^-$  denote the corresponding translations of the half-spaces  $H^+$  and  $H^-$ . The closure of a set  $A$  is denoted  $\bar{A}$ , its boundary  $\partial A$ .

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\*\* For example, the domination cone of the constant-sum three-person game has this property.

A closed set is said to be strictly convex if the open segment connecting any two of its points is in the interior of the set.

Theorem: Let  $C$  be bounded and convex; let  $\bar{C}$  and its dual be strictly convex; \*\*\* let  $H$  be a hyperplane through the origin, and let  $R$  be a cone which intersects  $H^+$  and  $H^-$ , but not  $H$ , and whose closure contains at least one of  $x$  and  $-x$  for every  $x$  in  $E^n$ . Then (1) has solutions of the form  
 $X = H_c \cap C.$

Proof: Define

$$X_c = H_c^- \cap (C - \partial C).$$

Let  $a$  be the greatest lower bound of those  $c$  for which  $X_c$  is not empty. The set  $(X_c + R)$  is open. For any point  $z$  in  $(X_c + R)$  can be written  $z = x + r$ , for some  $x \in X_c$ ,  $r \in R$ . Then the points of the form  $x' + \alpha r$ , for  $x' \in X_c$ ,  $\alpha > 0$  comprise an open set containing  $z$  and contained in  $(X_c + R)$ .

Lemma A: For all  $c > a$  sufficiently close to  $a$ ,

$$(2) \quad (X_c + R) \supseteq H_c^- \cap \bar{C}.$$

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\*\*\* Equivalently, at each boundary point there is a unique supporting hyperplane, and in each supporting hyperplane there is a unique boundary point. It follows that  $C$  is  $n$ -dimensional.  $C$  need not be closed.

Proof of Lemma A: Select  $r \in R \cap H^-$  and let  $\theta \leq \pi/2$  be the angle which  $r$  makes with the (negative) normal to  $H$ . Consider the set of all supporting hyperplanes to  $C$  whose normals (pointing out from  $C$ ) make angles of less than  $\pi/2 - \theta$  with the negative normal to  $H$ ; this set includes of course the supporting hyperplane  $H_a$ . The contact points of these hyperplanes with  $\partial C$  form a set  $U$  which is open in  $\partial C$ , since the supporting hyperplane is a continuous function of its contact point. It is possible to find a number  $c' > a$  such that

$$(3) \quad \bar{X}_c \cap \partial C \subseteq U \quad \text{all } c, \quad a < c < c'.$$

For otherwise we would have a sequence of points  $x_i$ , not in  $U$ :

$$x_i \in \bar{X}_{c_i} \cap \partial C, \quad \{c_i\} \rightarrow a,$$

which clearly must converge to a point in  $H_a \cap \bar{C} \cap U$ .

Granting (3), let  $y$  be any point in  $H_c^- \cap \bar{C}$ ,  $a < c < c'$ .

Project  $y$  parallel to  $r$  into a point  $y' \in H_c$  (see the figure).

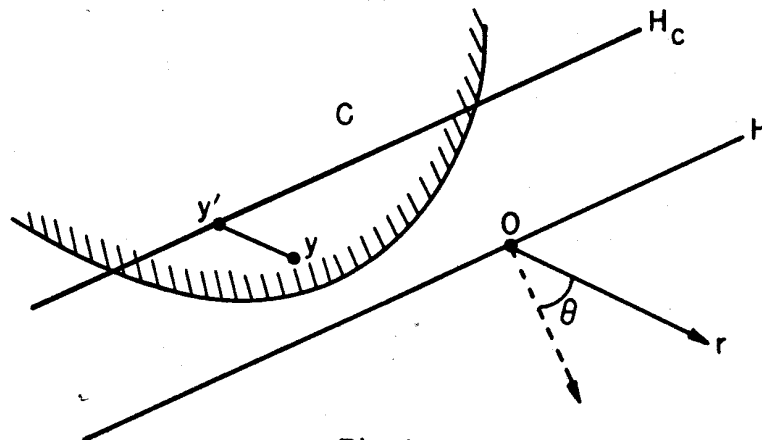


Fig. 1

It is clear that  $y \in (\{y'\} + R)$ ; we must therefore only show that  $y' \in X_c$ , that is, that  $y'$  is interior to  $C$ . But if  $y'$  is not interior, then some point of the segment joining  $y$  and  $y'$  must be in  $\partial C$ . The supporting hyperplane at this point will then make an angle of more than  $\pi/2 - \theta$  with  $H$ , giving us a contradiction. This completes the proof of the lemma.

Let  $c_0$  be the least upper bound of those  $c'$  such that (2) holds for all  $c < c'$ . There must be at least one point  $z_0$  in  $H_{c_0}^- \cap C$  not contained in  $(X_{c_0} + R)$ . This is true because the complement of  $(X_{c_0} + R)$  is a closed set which varies continuously with  $c$ .

Lemma B: For  $c_0$  as just defined,

$$(4) \quad (X_{c_0} + R) \supseteq H_{c_0}^+ \cap \bar{C}.$$

Proof of Lemma B: Take  $y \in H_{c_0}^+ \cap \bar{C}$ . The segment joining  $y$  and  $z_0$  meets  $H_{c_0}$  in a point  $x_0$ . By the strict convexity of  $\bar{C}$ ,  $x_0$  is interior to  $C$ , hence  $x_0 \in X_{c_0}$ . By the definition of  $z_0$ , the vector  $s = z_0 - x_0$  is not in  $R$ . For the same reason, the open set  $S$  of vectors of the form  $\alpha(z_0 - x)$ ,  $x \in X_{c_0}$ ,  $\alpha > 0$ , is also outside  $R$ , and  $S$  contains  $s$ . By our assumption on  $R$ , we must therefore have a sequence

of vectors  $\{r_i\} \rightarrow -s$  in  $R$ . We can use these to determine a sequence  $\{x_i\} \rightarrow x_0$  as follows:

$$x_i = y - \alpha_i r_i, \quad x_i \in H_{c_0}, \quad \alpha_i > 0.$$

Since  $X_{c_0}$  is open in  $H_{c_0}$ , the  $x_i$  will eventually lie in  $X_{c_0}$ . It follows that  $y \in (X_{c_0} + R)$ , as was to be shown.

Using again the continuity of the complement of  $(X_c + R)$  as a function of  $c$ , we see that (4) must hold over at least a small interval of values of  $c$  less than  $c_0$ , say, for  $c_1 < c < c_0$ . But within this interval, Lemma A applies. Therefore, for such a value of  $c$ , every point in  $C$  lies either in  $(X_c + R)$  or in  $H_c \cap C$ . This remains true if we replace  $X_c$  by its closure in  $C$ , that is, by  $H_c \cap C$ . Therefore,

$$H_c \cap C \supseteq C - ([H_c \cap C] + R) \quad (c_1 < c < c_0).$$

The reverse statement:

$$H_c \cap C \subseteq C - ([H_c \cap C] + R)$$

follows immediately from the fact that  $R$  and  $H$  are disjoint.

This completes the proof.





